

# Strong Lift-and-project cutting planes for the stable set problem

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joint work with

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# Outline

- Review of known relaxations:
  - LP in the natural space: *clique*, (lifted) *odd-hole*, *web*, *antiweb*, *rank* inequalities, etc.
  - SDP:
    - the Lovász  $\theta(G)$  relaxation
    - the Lovász-Schrijver lifting operator  $M_+(\cdot)$
  - LP in the extended (quadratic) space:
    - the Lovász-Schrijver  $M(K, K)$  operator
  - comparison among upper bounds
- $N_j(K, K)$ : A strong LP relaxation in the natural space (!)
  - theoretical strength of the closure  $\cap_{j \in V} N_j(K, K)$
  - practical implementation: Benders cuts
  - computational experience

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# Notation

$G = (V, E)$  simple undirected graph

A vertex set  $S \subseteq V$  is called *stable* if the vertices in  $S$  are pairwise non-adjacent

The *stable set problem* calls for a stable set of *maximum cardinality* (*weight*, if a weight vector  $w \in \mathbb{Q}^+$  is given)

$$\begin{aligned}\alpha_w(G) = \max \quad & \sum_{i \in V} w_i x_i \\ \text{s.t.} \quad & x_i + x_j \leq 1 \quad \forall \{i, j\} \in E \\ & x_i \in \{0, 1\} \quad \forall i \in V\end{aligned}\tag{1}$$

## Fractional Stable Set Polytope

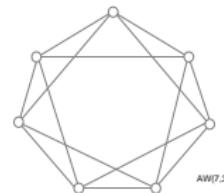
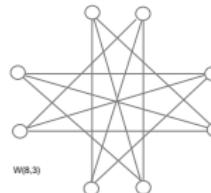
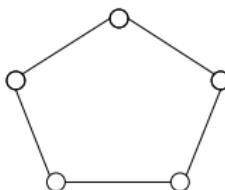
FRAC( $G$ ) = { $x \in \mathbb{R}^{|V|} : x_i \geq 0, \forall i \in V$  and (1) hold }

## Stable Set Polytope

STAB( $G$ ) convex hull of the incidence vectors of stable sets in  $G$ .

# Valid inequalities

- clique inequalities:  $\sum_{i \in C} x_i \leq 1$ ,  $C \subseteq V$  induces a maximal clique  
**QSTAB( $G$ )** polytope defined by clique and non-negativity inequalities
- rank inequalities:  $\sum_{i \in W} x_i \leq \alpha(G[W])$ ,  $W \subseteq V$
- special (structured) cases:  $W$  induces an *odd-hole*, *web*, *antiweb*, ...



- lifted versions (e.g. odd wheel inequalities)

# Computational experiences

1992	2001	2009
Nemhauser, Sigismondi	Rossi, S.	Rebennack, Oswald, Theis, Seitz, Reinelt, Pardalos
clique, (lifted) odd-hole	general rank inequalities	clique, odd-hole, rank, mod $k$ , local cuts
random $ V  \leq 120$	DIMACS $ V  \leq 700$ random $ V  \leq 200$	DIMACS $ V  \leq 500$ random $ V  \leq 150$

- clique inequalities are easy-to-manage and do close a relevant percentage of the gap
- effective separation heuristics for clique inequalities are important
- rank inequalities (and lifted odd-holes) can help especially on random graphs, but their contribution may be disappointing
- large enumeration trees are unavoidable to certify optimality (sparse graphs)

# The Lovász theta relaxation

$$\begin{aligned} \theta(G) = \max \quad & \sum_{i \in V} x_i \\ \text{s.t.} \quad & x_i = x_{ii} \quad (i \in V) \\ & x_{ij} = 0 \quad (\{i, j\} \in E) \\ & Y \in S_+^{n+1} \end{aligned}$$

where:

$$X = [x_{ij}]_{i=1, \dots, n; j=1, \dots, n}$$

$$Y = \begin{pmatrix} 1 & x^T \\ x & X \end{pmatrix}$$

$S_+^{n+1}$  denotes the cone of real symmetric square **psd** matrices of order  $n + 1$

# The Lovász theta relaxation

- polynomially solvable to arbitrary precision (Grötschel, Lovász and Schrijver, 1988)
- recent advances in practical implementations: Povh, Rendl, Wiegele '06; Malik, Povh, Rendl, Wiegele '07
- embedding  $\theta(G)$  in branch-and-bound looks now viable (Wilson'09), even if reoptimization can still be too slow
- $\text{STAB}(G) \subseteq \text{TH}(G) \subseteq \text{QSTAB}(G)$  [equality iff  $G$  is perfect]
- $\theta(G)$  is very strong in practice: [50 – 75]% gap closed w.r.t. the bound reached by aggressive clique separation (DIMACS graphs  $|V| \leq 300$ )

# Even stronger! The Lovász & Schrijver relaxation

The application of the Lovász & Schrijver M<sub>+</sub> operator to FRAC( $G$ ) is equivalent to adding to the Lovász (SDP) relaxation some linear inequalities:

$$\begin{array}{lll} x_{ij} \geq 0 & & \{i, j\} \notin E \\ x_{ik} + x_{jk} \leq x_k & & \{i, j\} \in E, k \neq i, j \\ x_i + x_j + x_k \leq 1 + x_{ik} + x_{jk} & & \{i, j\} \in E, k \neq i, j \end{array}$$

M<sub>+</sub>(FRAC( $G$ )) computationally challenging (even if still polynomial): much harder than just computing  $\theta$  (Burer & Vandenbussche, 2006)

Other attempts:

- Gruber & Rendl 03: add the "remaining" triangle inequalities
- Dukanovich & Rendl '07: weakened version

# SDP vs. LP relaxations

- Burer & Vandenbussche (2006).  $M_+(FRAC(G))$  is substantially tighter than the Sherali-Adams (LP) relaxation M( $FRAC(G)$ ):

Graph	$\alpha(G)$	$UB_{clique}$	M( $FRAC(G)$ )	$M_+(FRAC(G))$
brock200_2	12	21.53	66.66	17.08
brock200_4	17	30.84	66.66	22.84
c-fat200-5	58	66.67	66.66	58.17
mann_a9	16	18.50	18.00	17.17
hamming6-4	4	5.33	21.33	4.54
keller4	11	14.82	57.00	15.41
p_hat300_2	25	34.01	100.00	30.10
p_hat300_3	36	54.74	100.00	43.32
san200_0.7-2	18	21.14	66.66	20.01
sanr200_07	18	33.48	66.66	24.97
sanr200_09	42	60.04	66.66	49.31

- Balas, Ceria, Cornuejols and Pataki (1996). Lift-and-project, L&S lifting operators: including clique inequalities help, while PSD cuts do not look convenient

# The Lovász and Schrijver M(K, K) Operator

$K$  given linear system in 0 – 1 variables. For any pair of inequalities  $\alpha x - \beta \geq 0$  and  $\alpha^T x - \beta^T \geq 0$ , compute the 'product inequality':

$$\begin{pmatrix} -\beta & \alpha^T \end{pmatrix} Y \begin{pmatrix} -\beta^T \\ \alpha^T \end{pmatrix} \geq 0.$$

where products  $x_i x_j$ , for  $1 \leq i < j \leq n$ , are replaced by variables  $x_{ij}$  and terms  $x_i^2$ , for  $1 \leq i \leq n$ , by  $x_i$  (binary)

⇒ an extended formulation **provably stronger** than the original (Lovász and Schrijver '91).

Apply to: ( $\Omega$  set of all maximal cliques of  $G$ )

$$QSTAB(G) := \begin{cases} 1 - \sum_{i \in C} x_i \geq 0 & (C \in \Omega) \\ x_i \geq 0 & (i \in V) \end{cases}$$

# The M(QSTAB( $G$ ), QSTAB( $G$ )) relaxation

$$\max \sum_{i \in V} w_i x_i$$

s.t.

$$CVIs : -x_i + \sum_{j \in C: \{i,j\} \in \bar{E}} x_{ij} \leq 0 \quad (C \in \Omega, i \in V \setminus C)$$

$$CPIs : \sum_{i \in C \cup C'} x_i - \sum_{\{i,j\} \in \bar{E}(C:C')} x_{ij} \leq 1 \quad (C, C' \in \Omega)$$

$$x_{ij} = 0 \quad (\{i,j\} \in E)$$

$$x_{ij} \geq 0 \quad (\{i,j\} \in \bar{E})$$

- **non-compact:**  $n|\Omega|$  CVIs and  $|\Omega|(|\Omega| - 1)/2$  CPIs
- separation problems: both NP-hard (Giandomenico '06)

# On the strength of $M(K, K)$ : theory

$N(K, K)$  [ $N_+(K)$ ] projection of  $M(K, K)$  [ $M_+$ ] onto the non-quadratic space.

Relaxation	implied inequalities
$TH(G)$ proj. of the $\theta$ relaxation convex but not polyhedral	clique <a href="#">[Grotschel, Lovász and Schrijver '88]</a>
$N_+(FRAC(G))$ polytope	clique, odd-cycle, odd-antihole and odd-wheel <a href="#">[Lovász and Schrijver '91]</a> web <a href="#">[Giandomenico and Letchford '06]</a>
$N(QSTAB(G), QSTAB(G))$	web and antiweb and their lifted versions $\Rightarrow$ edge, clique, odd-hole, odd-antihole <a href="#">[Giandomenico, Letchford, Rossi, S. '07]</a>

# On the strength of M( $K, K$ ): practice

Graph	$V$	$ E $	$\alpha(G)$	$UB_{clique}$	$\theta(G)$	$UB_{MKK}$	DR07	BV06 M <sub>+</sub> (FRAC( $G$ ))
brock200_1	200	5,066	21	38.20	<b>27.5</b>	30.25	*	27.98
brock200_2	200	10,024	12	21.53	<b>14.22</b>	16.09	*	17.08
brock200_3	200	7,852	15	27.73	<b>18.82</b>	21.16	*	20.79
brock200_4	200	6,811	17	30.84	<b>21.29</b>	23.80	*	22.8
C.125.9	125	787	34	43.06	37.89	<b>36.53</b>	*	*
C.250.9	250	3,141	44	71.50	<b>56.24</b>	59.96	*	*
c-fat200-1	200	18,336	12	12.53	12	12	*	14.97
c-fat200-5	200	11,427	58	66.67	60.34	<b>58</b>	*	58.17
DSJC125.1	125	736	34	43.15	38.39	<b>36.99</b>	*	*
DSJC125.5	125	3,891	10	15.6	11.47	11.41	<b>11.4</b>	*
DSJC125.9	125	6,961	4	4.72	4.00	4	4.06	*
mann_a9	45	72	16	18.50	17.47	<b>16.85</b>	*	17.17
mann_a27	378	702	126	135.00	132.76	<b>131.39</b>	*	*
hamming6-4	64	1,312	4	5.33	5.33	4	4	4.54
keller4	171	5,100	11	14.82	14.01	<b>13.17</b>	*	15.41
p_hat300_1	300	33,917	8	15.68	<b>10.1</b>	11.40	*	18.66
p_hat300_2	300	22,922	25	34.01	<b>27</b>	30.00	*	30.1
p_hat300_3	300	11,460	36	54.74	<b>41.16</b>	47.32	*	43.32
san200_0.7-2	200	5,970	18	21.14	18	18	*	20.01
san200_0.9-3	200	1,990	44	45.13	44	44	*	44.4
sanr200_0.07	200	6,032	18	33.48	<b>23.8</b>	26.12	*	24.97
sanr200_0.09	200	2,037	42	60.04	<b>49.3</b>	50.73	*	49.31

# Benders reformulation $\Rightarrow$ N( $K, K$ )

<div style="border: 1px solid black; padding: 5px; display: inline-block;">cliques</div> <div style="border: 1px solid black; padding: 5px; display: inline-block;">CVIs + CPIs</div>	$\begin{array}{ll} \max \sum_{i \in V} w_i x_i \\ \text{s. t.} \\ Ax \leq 1 \\ Bx + Dy \leq d \\ x \in \mathbb{R}_+^n, y \in \mathbb{R}_+^p \end{array}$	$\begin{array}{ll} \max \sum_{i \in V} w_i x_i \\ \text{s. t.} \\ Ax \leq 1 \\ v^T(d - Bx) \geq 0, v \in \text{RAY} \\ \text{RAY :=} \\ \{\text{extreme rays of } \pi^T D \geq 0, \pi \geq 0\} \\ x \in \mathbb{R}_+^n \end{array}$
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Clever selection of Benders cuts accomplished by a *Cut Generating Linear Program* (CGLP) - Fischetti, Salvagnin, Zanette '08:

$$\min v^T(d - Bx^*)$$

$$v^T D \geq \mathbf{0}$$

$$\sum_{i=1,\dots,p} v_i = \mathbf{1}$$

$$v \geq \mathbf{0}$$

# Benders reformulation $\Rightarrow$ N( $K, K$ )

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$$\sum_{i=1,\dots,p} v_i = \mathbf{1}$$

$$v \geq \mathbf{0}$$

# Cut Generating LP

$i$  vertex,  $H, K$  cliques.

r = index of the (clique-vertex) pair  $Ki$

s = index of the (clique-clique) pair  $HK$

	$\cdots u_{Ki} \cdots$	$\cdots \cdots v_{HK} \cdots \cdots$	
	$\cdots x_i^* \cdots$	$\cdots (1 - x^*(H \cup K)) \cdots$	
	.....	.....	$\geq 0$
	$\vdots$	$\vdots$	$\vdots$
$(i, j) \in \bar{E}$	$a_{(i,j),(K,i)}$	$\cdots b_{(i,j)(H,K)} \cdots$	$\geq 0$
	$\vdots$	$\vdots$	$\vdots$
	.....	.....	$\geq 0$
	$\cdots 1 \cdots$	$\cdots 1 \cdots$	$= 1$

$a_{(i,j),(K,i)} = 1$  if  $j \in K$  and 0 otherwise;

$b_{(i,j)(H,K)} = -1$  if  $i \in H$  and  $j \in K$  and 0 otherwise

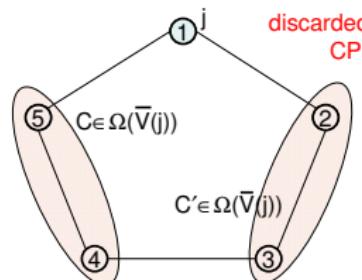
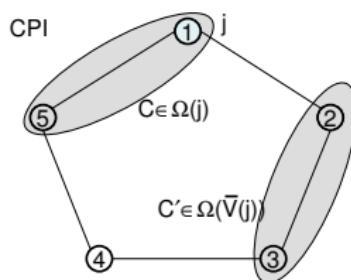
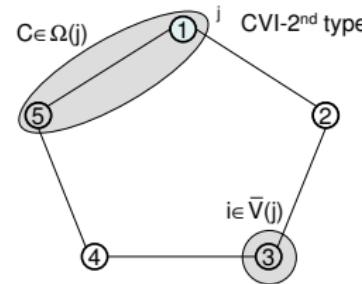
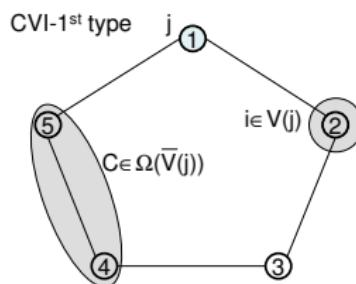
# Cutting plane performance

- sparse graphs are tractable up to  $\sim 150$  vertices (cut generation is too slow for  $|V| = 200$ )
- the integrality gap increases w.r.t.  $M(K, K)$ : the projection worsen about [2, 10]%
- some cuts are sparse and "clean", but some other are quite dense
- sometimes cuts are helpful in branch-and-cut, but often confound it
- different normalization constraints may change things, but do not seem resolute

# Relaxing M( $K, K$ )

- pick a vertex  $j$ ;  $\Omega(j)$  maximal cliques containing  $j$
- $\Omega(\bar{V}(j))$  maximal cliques with some vertex in  $\bar{V}(j)$  (non adjacent to  $j$ )

$$V(1) = \{2, 5\}, \bar{V}(1) = \{3, 4\}, \Omega(1) = \{1, 2\}, \{1, 5\}, \Omega(\bar{V}(1)) = \{2, 3\}, \{3, 4\}, \{4, 5\}$$



# The M<sub>j</sub>( $K, K$ ) relaxation

$$\max \sum_{i \in V} w_i x_i$$

s.t.

$$-x_i + \sum_{j \in C: \{i,k\} \in \bar{E}} x_{ik} \leq 0, \quad C \in \Omega(\bar{V}(j)), i \in j \cup V(j)$$

$$-x_i + \sum_{k \in C: \{i,k\} \in \bar{E}} x_{ik} \leq 0, \quad C \in \Omega(j), i \in \bar{V}(j)$$

$$\sum_{i \in C \cup C'} x_i - \sum_{\{i,k\} \in \bar{E}(C:C')} x_{ik} \leq 1, \quad C \in \Omega(j), C' \in \Omega(j) \cup \Omega(\bar{V}(j))$$

$$x_{ik} = 0, \quad \{i, k\} \in E$$

$$x_{ik} \geq 0, \quad i \in j \cup V(j), k \in \bar{V}(j)$$

# On the strength of N<sub>j</sub>( $K, K$ ): theory

Relaxation	implied inequalities
$TH(G)$ proj. of the $\theta$ relaxation convex but not polyhedral	clique [Grotschel, Lovász and Schrijver '88]
$N_+(FRAC(G))$ polytope	clique, odd-cycle, odd-anti-hole and odd-wheel [Lovász and Schrijver '91] web [Giandomenico and Letchford '06]
$N(QSTAB(G), QSTAB(G))$	web and antiweb and their lifted versions $\Rightarrow$ edge, clique, odd-hole, odd-anti-hole [Giandomenico, Letchford, Rossi, S. '07]
$\cap_{j \in V} N_j(QSTAB(G), QSTAB(G))$	odd-hole and antiweb and their lifted versions $\Rightarrow$ edge, clique, odd-anti-hole [Giandomenico, Rossi, S. '10] web? (we conjecture so)

# Implementation

- (aggressive) clique separation heuristic
- $\Omega(j)$  filtered by slack: prefer cliques tight to the current fractional point
- **Cut generation (one round)** for each  $i \in V$ :

STEP 1. build  $\Omega(j), \Omega(\bar{V}(j)) \subseteq \Omega$ , build CGLP

STEP 2. Solve CGLP; add violated Benders cuts

STEP 3. Run the clique separation heuristic;  
add violated clique cuts

- implemented in the IBM Cplex 11.2 framework; all default
- CGLPs solved by Cplex **hybaropt** option
- 2.4 GHz Pentium processor - 4 GB RAM

# Upper bounds comparison

Graph	$\alpha(G)$	$UB_{clique}$	$\theta(G)$	$UB$ M( $K, K$ )	time M( $K, K$ )	$UB$ $\cap N_j$	# cuts	time $\cap N_j$
brock200_1	21	38.20	27.50	30.25	17,670	33.71	240	405
brock200_2	12	21.53	14.22	16.09	26,501	18.27	25	343
brock200_3	15	27.73	18.82	21.16	22,386	23.57	64	413
brock200_4	17	30.84	21.29	23.80	25,362	26.77	144	446
<b>C.125.9</b>	34	43.06	<b>37.89</b>	36.53	227	<b>37.83</b>	624	506
C.250.9	44	71.50	56.24	59.96	9,397	63.95	500	8,908
c-fat200-5	58	66.67	60.34	58	265	58	68	45
<b>DSJC125.1</b>	34	43.15	<b>38.39</b>	36.99	274	<b>38.22</b>	623	335
DSJC125.5	10	15.6	11.47	11.41	377	13.93	99	27
<b>mann.a27</b>	126	135	<b>132.76</b>	131.39	393	<b>132.44</b>	378	79
mann.a45	345	360	358.99*	-	-	<b>355.79</b>	1,034	1,895
<b>hamming6-4</b>	4	5.33	<b>5.33</b>	4	4	<b>4.64</b>	123	31
keller4	11	14.82	14.01	13.82	15,324	14.55	171	14,073
p_hat300_2	25	34.01	27.00	30.00	24,337	31.55	128	958
p_hat300_3	36	54.74	41.16	47.32	46,408	49.79	407	2,419
san200_0.7-2	18	21.14	18	18	300	18	30	117
sanr200_07	18	33.48	23.8	26.12	9,971	29.45	297	762
sanr200_09	42	60.04	49.3	50.73	8,483	54.52	200	1254

$\cap_j N_j$  outperforms  $\theta(G)$

# Branch-and-cut-results

Graph	Cplex		Clique			$\cap_j N_j$		
	time	#sub	time	#sub	#clique cuts	time (sep. time)	#sub	#NKK cuts
brock200_1	1,784.78	270,169	1,474.88	91,543	1,492	<b>888.96</b> (15.36)	<b>60,248</b>	19
brock200_2	<b>83.16</b>	6,102	201.49	3,684	5,798	180.33 (25.77)	<b>1,875</b>	6
brock200_3	459.02	52,173	382.28	10,906	3,260	<b>303.19</b> (8.78)	<b>5,982</b>	9
brock200_4	735.52	85,134	724.14	24,835	2,584	<b>454.77</b> (10.74)	<b>13,381</b>	15
C125.9	5.63	3,049	4.16	2,357	192	<b>3.97</b> (1.39)	<b>2,287</b>	31
DSJC125.1	6.13	4,743	<b>5.11</b>	3,494	162	7.9 (3.3)	<b>2,640</b>	54
DSJC125.5	<b>6.97</b>	1,138	8.3	504	2,088	15.8 (6.7)	<b>436</b>	26
keller4	<b>21.88</b>	4,856	28.25	<b>2,730</b>	991	69.32 (41.72)	3,066	5
p_hat300_2	194.27	7,150	124.95	1,788	2,638	124.1 (7.3)	1,458	6
p_hat300_3	10,270.53	398,516	5,569.74	93,641	2,513	<b>3,469.52</b> (134.56)	<b>66,109</b>	38
sanr200_0.7	<b>827.52</b>	88,931	1,196.41	47,591	2,177	888.61 (37.19)	<b>30,965</b>	38
sanr200_0.9	2,650.55	635,496	1,529.2	355,867	366	<b>1,259.15</b> (30.46)	<b>267,708</b>	97
rand150_5	2.58	982.6	<b>2.15</b>	2,186.2	111.2	7.76 (5.62)	<b>798.6</b>	74.3
rand150_10	73.23	37,990.4	52.20	25,593.0	242.8	<b>48.13</b> (3.07)	<b>23,625.6</b>	81.3
rand150_20	108.90	31,646.4	<b>70.32</b>	12,284.0	584.60	82.67 (13.98)	<b>11,091.6</b>	95.0
rand200_5	705.03	320,921.0	545.76	320,362.4	202.0	<b>514.57</b> (17.09)	<b>186,450.3</b>	114.0
rand200_10	7,381.99	2,097,029.2	4,603.14	1,185,897.4	345.6	<b>3,160.56</b> (44.05)	<b>736,072.3</b>	120.6
rand200_20	4,261.68	670,879.4	2,598.74	246,003.4	1,007.4	<b>1,845.21</b> (207.94)	<b>137,387.6</b>	133.0

initial formulation: (good) collection of clique inequalities covering all edges  
times are in seconds

random: average of 5 graphs