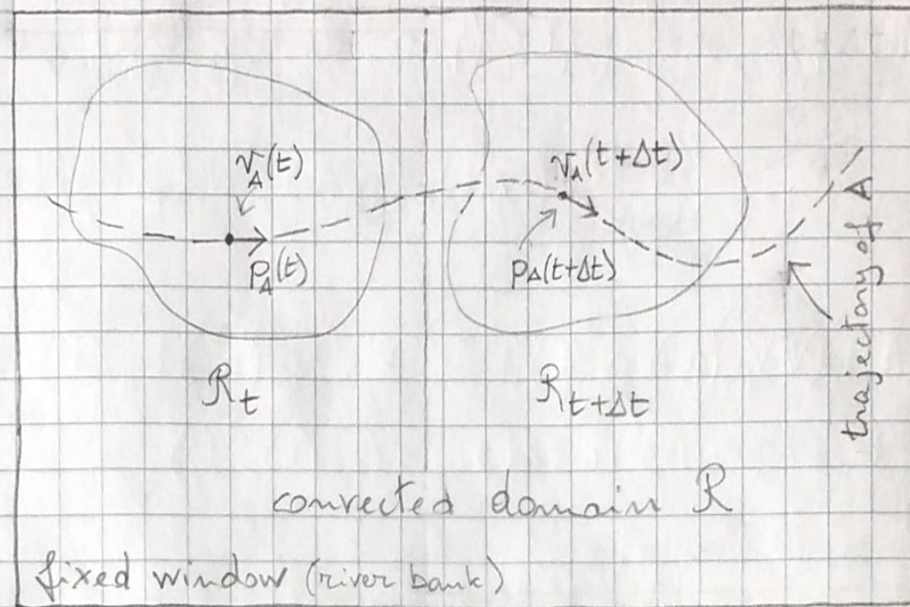


## Material description and spatial description



$$p_A(t), \quad v_A(t) = \dot{p}_A(t), \quad a_A(t) = \ddot{p}_A(t) \text{ acceleration}$$

Spatial description (over the fixed window)

$$v_t(x) = \dot{p}_A(t) \quad \text{with } x = p_A(t)$$

$$a_t(x) = \ddot{p}_A(t) \quad \text{with } x = p_A(t)$$

$$\ddot{p}_A(t) = \lim_{\Delta t \rightarrow 0} \frac{\dot{p}_A(t + \Delta t) - \dot{p}_A(t)}{\Delta t}$$

$$\dot{p}_A(t + \Delta t) = v_{t + \Delta t}(y), \quad y = p_A(t + \Delta t)$$

$$\lim_{\Delta t \rightarrow 0} \frac{v_{t + \Delta t}(p_A(t + \Delta t)) - v_t(p_A(t))}{\Delta t} = a(p_A(t))$$

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$$a(p_A(t)) = \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} \left( \underbrace{v_{t+\Delta t}(p_A(t+\Delta t))}_{-v_{t+\Delta t}(p_A(t))} - \underbrace{v_t(p_A(t))}_{+v_{t+\Delta t}(p_A(t))} \right)$$

$$a(p_A(t)) = (\nabla_{v_t(x)}) \dot{p}_A(t) + \frac{\partial}{\partial t} v_t(x), \quad x = p_A(t)$$

↑  
tangent vector to the trajectory

As a time dependent vector field over a fixed window it can be given the more descriptive form

$$a(x,t) = \nabla_{(x,t)} v(x,t) + \frac{\partial}{\partial t} v(x,t)$$

In short

$$a = (\nabla v)v + v'$$

## Newtonian fluids

$$\operatorname{div} \boldsymbol{v} = 0 \quad (\text{incompressibility})$$

$$\hat{\boldsymbol{T}}(\boldsymbol{F}) = 0 \quad (\text{no strain energy})$$

$$\boldsymbol{T}^+ = 2\mu \operatorname{sym} \nabla \boldsymbol{v} \quad (\text{viscous dissipation})$$

stress

$$\boldsymbol{T} = -p\boldsymbol{I} + 2\mu \operatorname{sym} \nabla \boldsymbol{v}$$

force balance

$$\operatorname{div} \boldsymbol{T} + \boldsymbol{b} = 0$$

$$\operatorname{div} \boldsymbol{T} = -\operatorname{div}(p\boldsymbol{I}) + \mu(\operatorname{div} \nabla \boldsymbol{v} + \operatorname{div} \nabla \boldsymbol{v}^T)$$

$$\operatorname{div}(p\boldsymbol{I})\boldsymbol{e} = \operatorname{div}(p\boldsymbol{e}) = \operatorname{tr}(\nabla(p\boldsymbol{e}))$$

$$= \operatorname{tr}(\boldsymbol{e} \otimes \nabla p) = \nabla p \cdot \boldsymbol{e} \Rightarrow \operatorname{div}(p\boldsymbol{I}) = \nabla p$$

$$\operatorname{div} \nabla \boldsymbol{v} = \Delta \boldsymbol{v} \quad (\text{Laplacian})$$

$$\operatorname{div} \nabla \boldsymbol{v}^T = \nabla(\operatorname{div} \boldsymbol{v}) = 0$$

$\searrow 0$

$$\operatorname{div} \boldsymbol{T} = -\nabla p + \mu \Delta \boldsymbol{v}$$

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$$b = b^{in} + b_o \quad (\text{bulk force density})$$

↑ inertial force density

$$b^{in} = -\rho a$$

← mass density  
← acceleration field

with

$$a = (\nabla v) v + v' \quad (\text{spatial description})$$

Replacing the expressions for  $\text{div} T$  and  $b$  into the balance equation we get the Navier-Stokes equation

$$-\nabla p + \mu \Delta v + \rho (\nabla v) v + \rho v' + b_o = 0$$